Data-driven Model Selection for Approximate Bayesian Computation via Multiple Logisitic Regression.

### Ben Rohrlach

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3 Model Selection.







• Consider the Beringian Steppe Bison.



## Some motivation.





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- Population numbers dropped at *some time* in the past.
- Did it happen slowly over time?
- Did it happen abruptly?
- If it did happen abruptly, when did it happen?
- How can we work this out if all we have are some DNA from old bones??

seq1 0	TTCCGTTATGCGATATGCTTAGTAGAATAAAGATGGAGCGAGTACACATACTCTCTGATCTTTGCGCTGAACGCCGTCGTGAGGTGCGTCGTAACACTTAATTC
seq2_0	ATCCCTTATGTAATACTCGGCGTAAAATGAAGATGTGGCCAGTACGGATACTATCTGATCTTTGTGGTGATCGCGAGCGTGAGGTTGGTCGCGATACTAAATTT
seq3_0	ATCCCTTATGTAATCCTCGCCGTGGAATGAAGGTGGGGCGACTACGAATACTATATGACCTCTGTGGCGATCTCGGGGCGTGAGGTTTGTCGCGACAGTTAATTT
seq4_0	ATCCCTTATTTAATACTCGGCGTAAAATGAAGATGGGGCCAGTACGGATACTATCTGATCTTTGTGGCGATCGAGAGCGTGAGGTTCGCCGCGACACTAAATTA
seq5_0	ATCCCTTATGTGACACTCGGCGTGGAATGAAGATGGGTCGAGTAAGAATACTTTCTGATCTTCGTGGCGGGCG
seq6_0	ATCCCTTATTTAATACTCGGCGTAAAATGAAGATGGGGCCAGTACGGATACTATCTGATCTTTGTGGCGATCGAGAGCGTGAGGTTCGTCGCGACACTAAATTA
seq7_0	ATCCCTTATGTAATCCTCGGCGTGGAATGAAGATGGGGCGACTACGAATACTATCTGACCTCTGTGGCGATCGCGGGGTGTGAGGTTTGTCGCGACACTTAATTT
seq8_0	ATCCCTTATGTAATCCTCGCCGTGGAATGAAGGTGGGGGGGG



## Some motivation.



Radiocarbon years before present

Figure: Rise and fall of the Beringian steppe bison, Shapiro et al. [4].

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**Bayesian Approach** 



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 Data comes from a repeatable experiment. Bayesian Approach

 Data comes from a realised experiment.



- Data comes from a repeatable experiment.
- The parameters are constant.

Bayesian Approach

- Data comes from a realised experiment.
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- Set  $\alpha$  in advance and find  $L(\boldsymbol{X}|H_0)$ ,
- Accept  $H_0$  if  $L(\boldsymbol{X}|H_0) \geq \alpha$ ,
- Report point estimates and confidence intervals for parameters.

In a Bayesian analysis we:

• From  $\pi(\theta)$  we (inductively) find  $P(\theta|\mathbf{X})$ ,



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- From  $\pi(\theta)$  we (inductively) find  $P(\theta | \mathbf{X})$ ,
- Describe the *posterior* distribution of  $\theta$ ,
- Report highest posterior density intervals for parameters.

### That is:

• We aim to describe the probability of model parameters *given* the data we have observed via

$$P(\theta | \mathbf{X}) = rac{L(\mathbf{X} | \theta) \pi(\theta)}{P(\mathbf{X})}$$

where  $L(\mathbf{X}|\boldsymbol{\theta})$  is the likelihood function for the data.

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$$P( heta ig m{x}) = rac{L(m{x}ig heta) \pi(m{ heta})}{P(m{x})}$$

where  $\pi(\theta)$  is the 'prior distribution' for  $\theta$  (my prior beliefs about the possible parameter values).

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$$m{P}(m{ heta}ig|m{X}) = rac{L(m{X}ig|m{ heta})\pi(m{ heta})}{m{P}(m{X})}$$

where P(X) is the 'marginal likelihood' of the data (sometimes called the 'model evidence').

• First considered by Donald Rubin in the 1980's via the 'Acceptance-Rejection Algorithm' [1].



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- Particularly useful when obtaining the likelihood function  $L(\mathbf{X}|\theta)$  is difficult or impossible to obtain.
- Relies on being able to simulate data efficiently.

- Consider obtaining l posterior samples using some observed data X<sub>obs</sub>:
- 1: Set *i* = 0
- 2: while *i* < ℓ do

#### 9: end while



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- Extremely slow convergence in cases where our data has high dimensionality.
- Could consider accepting data that is 'close enough'.
- If " $X^* = X_{obs}$ " is unrealistic, try " $X^* \approx X_{obs}$ "
For some distance function ρ(X, Y), and some 'tolerance' parameter ε, the algorithm now becomes:



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- 5: if  $(\rho(X^*, X_{obs}) < \epsilon)$  then
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• Gives an approximate posterior distribution  $P(\theta | \hat{X}_{obs})$ .



Gives an approximate posterior distribution P(θ|𝑋<sub>obs</sub>).
P(θ|𝑋<sub>obs</sub>) → P(θ|𝑋<sub>obs</sub>) as ϵ → 0.



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- Still slow convergence for small  $\epsilon$ .
- Data being 'similar' can still be very unlikely.

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- Summary statistics are used to reduce the dimensionality of data.



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- Sufficient summary statistics contain all of the information about a parameter that is available in a sample (i.e.  $\bar{X}$  is sufficient for  $\mu$ ).
- A summary statistic *S*(*X*) is sufficient if it can be written in Fisher-Neymann factorised form:

$$L(\boldsymbol{X}|\boldsymbol{ heta}) = g(\boldsymbol{X})h_{\boldsymbol{ heta}}(\boldsymbol{S}(\boldsymbol{X})|\boldsymbol{ heta})$$

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- It can be shown  $P(\theta | \boldsymbol{X}_{obs}) = P(\theta | S(\boldsymbol{X}_{obs})).$
- That is, we can compare sufficient summary statistics to obtain the exact posterior distribution for θ.

- For some distance function ρ(S(X), S(Y)), and some 'tolerance' parameter ε, the algorithm now becomes:
- 1: Set *i* = 0
- 2: **while** *i* < ℓ **do**
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- Convergence can now be faster.
- Sufficient summary statistics rarely show up when required.
- Choosing a 'best summary statistic' was the focus of my Masters [2].

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- For each n ∈ {1, · · · , P} perform linear regression on the TrainDat such that we can get predictions

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• We now have a 'best predicted parameter value' if we have summary statistics.

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How do we choose which model we might wish to simulate data under?



• Consider models  $\mathcal{M} = \{M_1, \cdots, M_q\}$ 



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- We can add a step which selects which model we might simulate under.

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- How can we choose which M<sub>i</sub> best fits our data?
- Common approach is to use 'Bayes Factors'  $B_{ij}$ ,  $i \neq j \in \{1, \dots, q\}$ .




$$m{B}_{ij} = rac{m{P}\left(m{X}ig|m{M}_{i}
ight)}{m{P}\left(m{X}ig|m{M}_{j}
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$$B_{ij} = \frac{P\left(\boldsymbol{X} | M_{i}\right)}{P\left(\boldsymbol{X} | M_{j}\right)}$$
$$= \frac{P\left(M_{i} | \boldsymbol{X}\right) P\left(\boldsymbol{X}\right) / R(M_{i})}{P\left(M_{j} | \boldsymbol{X}\right) P\left(\boldsymbol{X}\right) / R(M_{j})}$$



$$\begin{split} \boldsymbol{B}_{ij} &= \frac{P\left(\boldsymbol{X} \middle| \boldsymbol{M}_{i}\right)}{P\left(\boldsymbol{X} \middle| \boldsymbol{M}_{j}\right)} \\ &= \frac{P\left(\boldsymbol{M}_{i} \middle| \boldsymbol{X}\right) P\left(\boldsymbol{X}\right) / R(\boldsymbol{M}_{i})}{P\left(\boldsymbol{M}_{j} \middle| \boldsymbol{X}\right) P\left(\boldsymbol{X}\right) / R(\boldsymbol{M}_{j})} \\ &= \frac{P\left(\boldsymbol{M}_{i} \middle| \boldsymbol{X}\right)}{P\left(\boldsymbol{M}_{j} \middle| \boldsymbol{X}\right)}, \end{split}$$

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if  $R(\cdot)$  has a uniform distribution.

$$B_{ij} = rac{P(M_i | \boldsymbol{X})}{P(M_j | \boldsymbol{X})}.$$



$$m{\mathsf{B}}_{ij} = rac{m{\mathsf{P}}\left(m{\mathsf{M}}_{i}ig|m{X}
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- This is just the 'posterior ratio' for Models *i* and *j*.
- Imagine out of 300 retained posterior parameter samples: 200 are from model *i*, and 100 are from model *j*,

$$\implies B_{ij} = \frac{200/300}{100/300} = 2.$$

It can be shown that [3]:

$$B_{ij} = \frac{P\left(M_{i} | \boldsymbol{X}\right)}{P\left(M_{j} | \boldsymbol{X}\right)} \times \frac{h_{j}\left(\boldsymbol{X} | \boldsymbol{S}(\boldsymbol{X})\right)}{h_{i}\left(\boldsymbol{X} | \boldsymbol{S}(\boldsymbol{X})\right)}$$



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$$= \frac{P\left(M_{i} | \boldsymbol{X}\right)}{P\left(M_{j} | \boldsymbol{X}\right)}$$
$$\iff h_{j}\left(\boldsymbol{X} | \boldsymbol{S}(\boldsymbol{X})\right) = h_{i}\left(\boldsymbol{X} | \boldsymbol{S}(\boldsymbol{X})\right)$$



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$$\begin{split} \boldsymbol{B}_{ij} &= \frac{P\left(\boldsymbol{M}_{i} | \boldsymbol{X}\right)}{P\left(\boldsymbol{M}_{j} | \boldsymbol{X}\right)} \times \frac{h_{j}\left(\boldsymbol{X} | \boldsymbol{S}(\boldsymbol{X})\right)}{h_{i}\left(\boldsymbol{X} | \boldsymbol{S}(\boldsymbol{X})\right)} \\ &= \frac{P\left(\boldsymbol{M}_{i} | \boldsymbol{X}\right)}{P\left(\boldsymbol{M}_{j} | \boldsymbol{X}\right)} \\ & \Longleftrightarrow h_{j}\left(\boldsymbol{X} | \boldsymbol{S}(\boldsymbol{X})\right) = h_{i}\left(\boldsymbol{X} | \boldsymbol{S}(\boldsymbol{X})\right) \end{split}$$

• That is, *B<sub>ij</sub>* will be biased unless the probability of seeing the data, given the observed summary statistics, is equal for each model.

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- Posterior distributions are sensitive to choices of prior distributions.
- A particularly poor choice of π<sub>j</sub>(θ) may reduce the number of retained simulations under Model j, and hence inflate B<sub>ij</sub>.

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• We would like a model selection algorithm that avoids comparing posterior distributions.



- We would like a model selection algorithm that avoids comparing posterior distributions.
- Given that our 'semi-automatic summary selection' version ABC is an example of 'supervised learning', we could consider a similar method for model selection.

 Let X be our data (the collection of Γ × T summary statistics),



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- Let  $\mathbf{x}^m = (s_1^m, \cdots, s_T^m)$  be the  $m^{\text{th}}$  row of  $\mathbf{X}$  (the summary statistics from the  $m^{\text{th}}$  simulation).



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- Let β<sup>c</sup> = (β<sup>c</sup><sub>0</sub>, · · · , β<sup>c</sup><sub>T</sub>) be the vector of coefficients for category *c*.



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- We aim to best fit the model

$$\ln\left(\frac{P(Y^m=c|\boldsymbol{X})}{P(Y^m=q|\boldsymbol{X})}\right) = \beta^c \cdot \boldsymbol{X}^{\prime},$$

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for  $c = 1, \cdots, J - 1$ .

• We end up with a predictive model such that we can predict for *X*<sub>NEW</sub>:

$$P(Y^m = c | \boldsymbol{X}_{NEW}) = p_c$$

for each  $c \in \{1, \cdots, q\}$ , such that

$$\sum_{i=1}^{q} p_i = 1.$$



Consider two opposing models of population dynamics:



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- The Bottleneck Model:
  - A sudden reduction to between 20% and 40% of the effective population size occurs before the species dies out.
- The Exponential Model:
  - There was no sudden population size reduction, the species just died out (relatively) slowly over 3000 generations.

- However, we don't know which model fits our data best.
- If the data came from the Bottleneck Model, my prior belief is that: N(16000) = 150,000, N(15500) ∼ U(30,000,75,000) and N(12000) ∼ U(300,12500).
- If the data came from the Exponential Model, my prior belief is that: *N*(16000) = 150,000, *N*(15500) = 150,000 and *N*(12000) ∼ *U*(300,7500).

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- I then produced another 10,000 independent simulations (call this testDat).



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Recall the two opposing models of population dynamics:



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IDF

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