

# Distinguishing Convergence Periods on Phylogenetic Networks

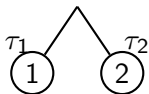
Jonathan Mitchell

Supervisors: Barbara Holland, Jeremy Sumner

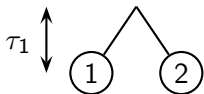
University of Tasmania

November 7, 2013

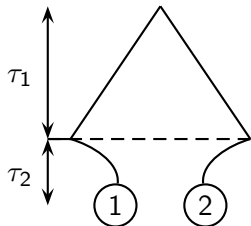
## Introduction



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non-clock-like tree.



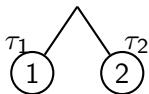
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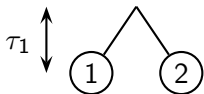
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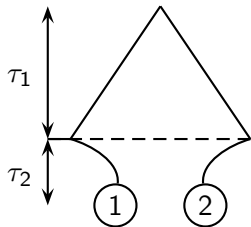
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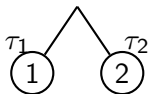
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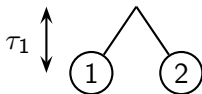
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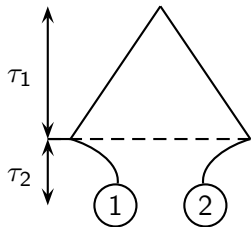
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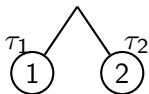
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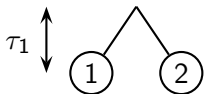
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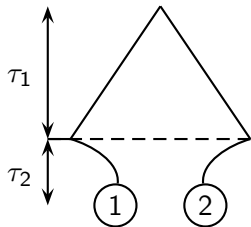
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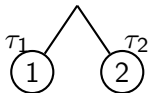
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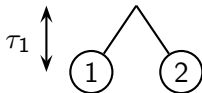
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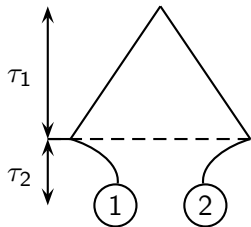
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- Two networks are said to be **distinguishable** if their probability spaces are not identical.

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- Assumption is that the observed frequencies are samples from the probability distribution for some model. eg.  $p_{CCC} \approx \frac{f_{CCC}}{N} = \frac{1}{5}$ .

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- Give preference to tree if tree and convergence network cannot be distinguished.

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- Binary symmetric model is the simplest model and its generators form an abelian (or commutative) group.
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- Probability distributions will be given in the Hadamard basis.

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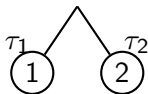
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- From here we can compare the probability spaces of competing trees and networks.



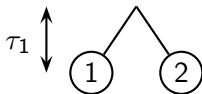
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- We will now look at the two and three-taxon cases as examples.

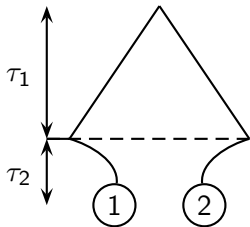
## Two-Taxon Networks



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Two-taxon clock-like  
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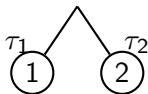


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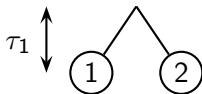
- In the Hadamard basis, the probability distribution for network 1 is

$$\hat{P} = \begin{bmatrix} q_{00} \\ q_{01} \\ q_{10} \\ q_{11} \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \\ 0 \\ e^{-(\tau_1 + \tau_2)} \end{bmatrix}.$$

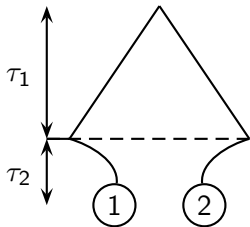
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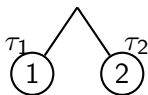
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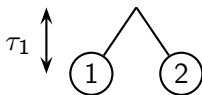
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$$\hat{P} = \begin{bmatrix} q_{00} \\ q_{01} \\ q_{10} \\ q_{11} \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \\ 0 \\ e^{-2\tau_1} \end{bmatrix}.$$

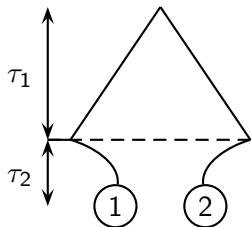
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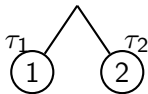


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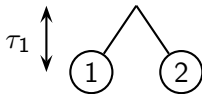
- In the Hadamard basis, the probability distribution for network 3 is

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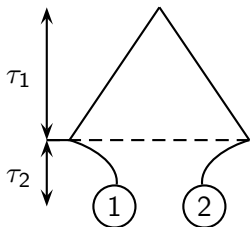
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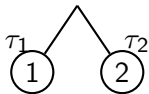
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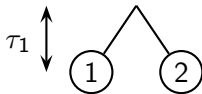
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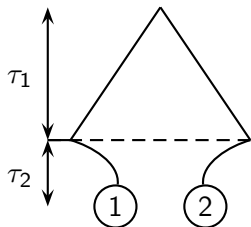
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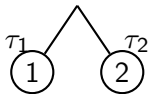
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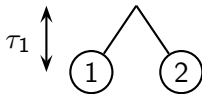
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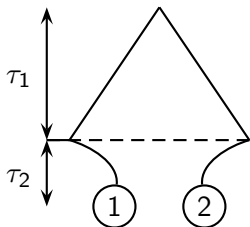
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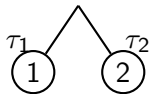
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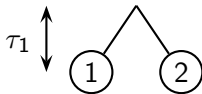
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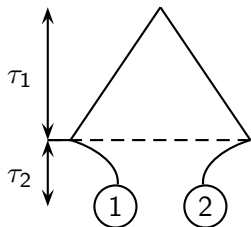
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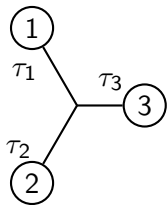


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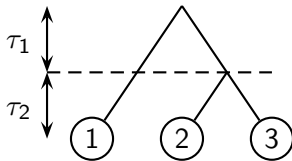
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- Probability spaces are identical.
- Networks are not distinguishable.
- No reason to introduce convergence periods for two-taxon trees under our models.



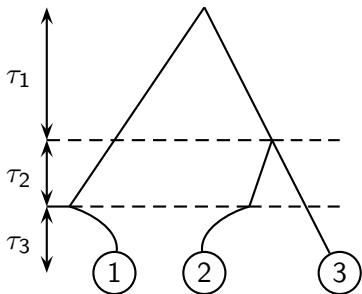
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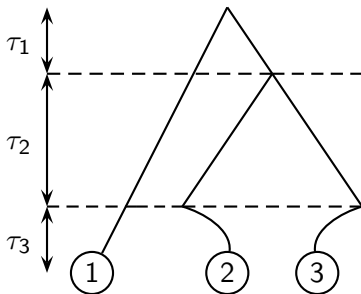
Network 1



Network 2

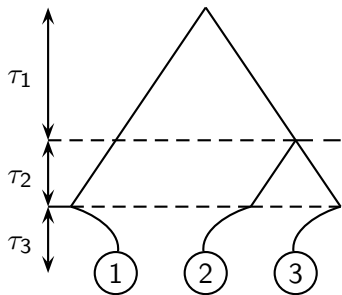


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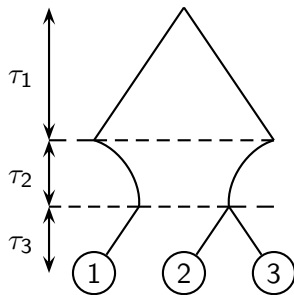


Network 4

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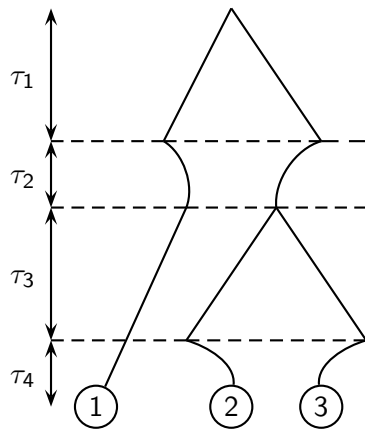
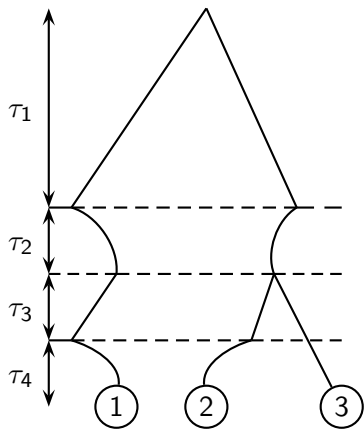


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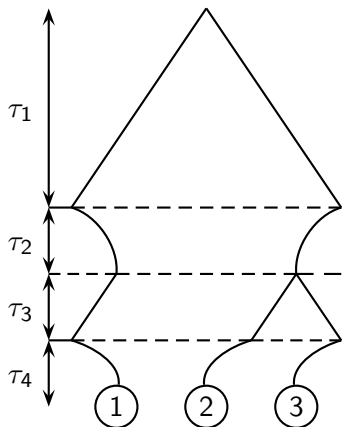


Network 6

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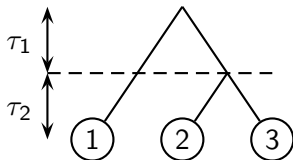


## Three-Taxon Networks



Network 9

## An Example: Three-Taxon Clock-Like Tree



Three-taxon clock-like tree with no convergence periods

- In the Hadamard basis, the probability distribution is

$$P = \begin{bmatrix} q_{000} \\ q_{001} \\ q_{010} \\ q_{011} \\ q_{100} \\ q_{101} \\ q_{110} \\ q_{111} \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \\ 0 \\ e^{-2\tau_2} \\ 0 \\ e^{-2(\tau_1+\tau_2)} \\ e^{-2(\tau_1+\tau_2)} \\ 0 \end{bmatrix}.$$

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- Since the  $\tau$ 's are time parameters,  $\tau_i \geq 0$  for all  $i$ .
- To solve the equations we must first make the substitutions  $x_i = e^{-\tau_i}$ . This forces all of the probability distribution equations to be polynomial equations in the form

$$q_{i_1 i_2 \dots i_n} = f(x_1, x_2, \dots, x_m),$$

where  $n$  is the number of taxa and  $m$  is the number of time parameters.

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- We now rearrange the equations to evaluate to zero on the model,

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- We then extract the polynomials,  $f(x_1, x_2, \dots, x_m) - q_{i_1 i_2 \dots i_n}$ , from the polynomial equation and make them the generating polynomials of an ideal.

## Comparing Probability Spaces

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- Now that we have an ideal generated by polynomial equations we can solve these polynomial equations.

# Comparing Probability Spaces

## Definition

For any set of polynomials,  $f_1, f_2, \dots, f_s \in \mathbb{F}[x_1, x_2, \dots, x_m]$ , we can define the set  $I = \langle f_1, f_2, \dots, f_s \rangle$ , as follows:

$$I = \langle f_1, f_2, \dots, f_s \rangle = \left\{ \sum_1^s h_i f_i : h_1, h_2, \dots, h_s \in \mathbb{F}[x_1, x_2, \dots, x_m] \right\}.$$

A key result is that  $I = \langle f_1, f_2, \dots, f_s \rangle$  meets the definition of an *ideal* for *any* polynomials  $f_1, f_2, \dots, f_s \in \mathbb{F}[x_1, x_2, \dots, x_m]$ . For the three-taxon clock-like tree, our set of generating polynomials is  $\{x_2^2 - q_{011}, x_1^2 x_2^2 - q_{101}, x_1^2 x_2^2 - q_{110}\}$ , which forms the ideal  $I = \langle x_2^2 - q_{011}, x_1^2 x_2^2 - q_{101}, x_1^2 x_2^2 - q_{110} \rangle$ .

# Comparing Probability Spaces

- Definition (Gröbner Basis)

Fix a monomial order. A finite subset  $G = \{g_1, \dots, g_t\}$  of an ideal  $I$  is said to be a **Gröbner basis** (or **standard basis**) if  $\langle LT(g_1), \dots, LT(g_t) \rangle = \langle LT(I) \rangle$ .

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- By applying the constraints on the  $\tau$ 's, we can find all of the constraints on the  $q$ 's.

## Comparing Probability Spaces

- Going back to our example, the system of equations (after turning them into polynomials) was  $\{x_2^2 - q_{011} = 0, x_1^2 x_2^2 - q_{101} = 0, x_1^2 x_2^2 - q_{110} = 0\}$ .

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- We will now compare some three-taxon examples.

## Three-Taxon Networks

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1	N	N	N
2, 4, 5, 6, 8, 9	Y	Y	N
3, 7	N	Y	Y

Summary of network constraints which must be met.

## Three-Taxon Networks

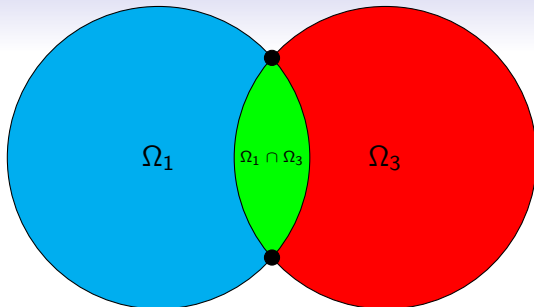
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Summary of network constraints which must be met.

- In addition, the non-clock-like tree (network 1) must meet the constraints

$$\{q_{011} \geq q_{101}q_{110}, q_{101} \geq q_{011}q_{110}, q_{110} \geq q_{011}q_{101}\}.$$



Probability spaces of the networks. The probability space for network 2 is the two black dots where the probability spaces for networks 1 and 3 intersect.

Colour	Probability Space	Constraints
Blue	$\Omega_1$	$\{q_{011} \geq q_{101} q_{110}, q_{101} \geq q_{011} q_{110}, q_{110} \geq q_{011} q_{101}\}$
Red	$\Omega_3$	$\{q_{011} \geq q_{101}, q_{110} \geq q_{101}, q_{011}(1 - q_{110})^2 \geq (q_{011} - q_{101})^2\}$
Green	$\Omega_1 \cap \Omega_3$	$\{q_{011} \geq q_{101}, q_{110} \geq q_{101}, q_{101} \geq q_{011} q_{110}\}$
Black	$\Omega_1 \cap \Omega_2 \cap \Omega_3$	$\{q_{101} = q_{110}, q_{011} \geq q_{110}\}$

Summary of network constraints which must be met in the region of the probability space.

- In summary, there are four distinct regions in the probability space of the networks. The probability space either belongs to the non-clock-like tree exclusively, the clock-like network with convergence exclusively, either of the non-clock-like tree or the clock-like network with convergence, or all three networks.

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- Consequently, the three-taxon clock-like network with convergence is a viable model of evolution.
- Next step is to compare the fit of the three networks to a given dataset.
- Further work could involve extending the results to more taxa or to more complicated Abelian models beyond the binary symmetric model.