

# Algebraic constraints on the transition probability matrices produced from Lie-Markov models

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## Some algebraic definitions

- ▶ Take  $\mathcal{L} \subseteq \text{Mat}_n(\mathbb{R})$  to be a **linear** subspace of matrices  
i.e.  $A, B \in \mathcal{L} \implies A + \lambda B \in \mathcal{L}$
- ▶  $\mathcal{L}$  is an ‘algebra’ if it is closed under a ‘product’ (binary operation):
  - (i.) **Matrix algebra:**  $AB \in \mathcal{L}$
  - (ii.) **Lie algebra:**  $[A, B] := AB - BA \in \mathcal{L}$
  - (ii.) **Jordan algebra:**  $\{A, B\} := AB + BA \in \mathcal{L}$

(Were ‘ $AB$ ’ is the usual matrix product we all know and love!)

## Continuous time Markov chains for DNA evolution

- ▶ Generator matrix  $Q \rightarrow P = e^{Qt}$ , transition matrix
- ▶ Exemplar **DNA** (A,G,C,T) models:

### 'Strand symmetric'

(Casanelas, Sullivant, 2005)

$$\begin{array}{c} A \\ G \\ C \\ T \end{array} \begin{array}{c} A \\ G \\ C \\ T \end{array} \begin{bmatrix} * & \alpha & \beta & \gamma \\ \delta & * & \epsilon & \kappa \\ \kappa & \epsilon & * & \delta \\ \gamma & \beta & \alpha & * \end{bmatrix}$$

### 'HKY'

(Hasegawa, Kishino, Yano, 1985)

$$\begin{array}{c} A \\ G \\ C \\ T \end{array} \begin{array}{c} A \\ G \\ C \\ T \end{array} \begin{bmatrix} * & \kappa\alpha_G & \alpha_C & \alpha_T \\ \kappa\alpha_A & * & \alpha_C & \alpha_T \\ \alpha_A & \alpha_G & * & \kappa\alpha_T \\ \alpha_A & \alpha_G & \kappa\alpha_C & * \end{bmatrix}$$

- ▶ Strand symmetric:  $\text{rate}(A \rightarrow G) = \text{rate}(T \rightarrow C)$
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## Multiplicative closure for CTMCs

- ▶ Transition matrices are multiplicative:  $(P_1, P_2) \rightarrow P_1 P_2$   
But what about a particular model?
- ▶ If  $P_1 = e^{Q_1 t_1}$  and  $P_2 = e^{Q_2 t_2}$  then  $P_1 P_2 = e^{Q(t_1+t_2)}$   
i.e. same transition rates, longer time
- ▶ If the transition rates change:

**Commuting case:**  $Q_1 Q_2 = Q_2 Q_1$ ,

$$P_1 P_2 = e^{Q_1 t_1} e^{Q_2 t_2} = e^{Q_1 t_1 + Q_2 t_2}$$

**General case:**

$$\begin{aligned} P_1 P_2 &= e^{Q_1 t_1} e^{Q_2 t_2} = e^{Q_1 t_1 + Q_2 t_2 + (\text{infinite series of corrections})} \\ &= e^{Q_1 t_1 + Q_2 t_2 + \frac{1}{2} t_1 t_2 [Q_1, Q_2] + \dots} \end{aligned}$$

where  $[Q_1, Q_2] = Q_1 Q_2 - Q_2 Q_1$  measures non-commutativity.

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## Some models are multiplicative closed, some are not

- ▶ Necessary and sufficient condition for closure (roughly): generators span a **Lie algebra**  $\mathcal{L}$  :  $Q_1 + \lambda Q_2$  and  $[Q_1, Q_2] \in \mathcal{L}$
- ▶ Strand-symm model is closed because the products  $Q_1 Q_2 \in \mathcal{L}$ :

$$Q_1 Q_2, Q_2 Q_1 \in \mathcal{L} \text{ (and linearity)} \implies [Q_1, Q_2] = Q_1 Q_2 - Q_2 Q_1 \in \mathcal{L}$$

So some models form **matrix algebras** and we observe:

$$\text{matrix algebra} \implies \text{Lie algebra} \iff \text{mult. closed}$$

- ▶ HKY is not closed because it is non-linear:

$$Q = \begin{pmatrix} * & \kappa\alpha_G & \alpha_C & \alpha_T \\ \kappa\alpha_A & * & \alpha_C & \alpha_T \\ \alpha_A & \alpha_G & * & \kappa\alpha_T \\ \alpha_A & \alpha_G & \kappa\alpha_C & * \end{pmatrix} \implies Q_{12}Q_{13} = Q_{43}Q_{42}, \text{ etc.}$$

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## Structure of models that form matrix algebras

- ▶ A model where the generators span a matrix algebra is always closed:

$$e^Q = \mathcal{I} + (Q + Q^2/2 + \dots) = \mathcal{I} + \hat{Q}$$
$$\implies e^{Q_1} e^{Q_2} = (\mathcal{I} + \hat{Q}_1)(\mathcal{I} + \hat{Q}_2) = \mathcal{I} + (\hat{Q}_1 + \hat{Q}_2 + \hat{Q}_1 \hat{Q}_2)$$

i.e. closure under sums and products is sufficient (although the latter is not necessary. . .)

- ▶ Easy to infer the structure of the transition matrices:

$$\mathcal{M} = \mathcal{I} + \mathcal{L}$$

i.e. “**transition matrix** =  $\mathcal{I}$  + **generator**”

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- ▶ e.g., **symmetric** generators do not form a Lie algebra:

$$(Q_1 Q_2)^T = Q_2^T Q_1^T = Q_2 Q_1 \neq Q_1 Q_2 \quad \text{and} \quad [Q_1, Q_2]^T = -[Q_1, Q_2]$$

However,

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## Not all multiplicatively closed models satisfy “ $\mathcal{M} = \mathcal{I} + \mathcal{L}$ ”

- ▶ Toy model  $\mathcal{L}$ :

$$Q = \begin{pmatrix} * & \alpha + \beta & 2\beta \\ 0 & 0 & 0 \\ 2\alpha & \alpha + \beta & * \end{pmatrix}$$

Intentionally designed so  $[Q_1, Q_2] \in \mathcal{L}$  but  $Q_1 Q_2 \notin \mathcal{L}$

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- ▶ This Lie algebra is “algebraic”  $\implies \mathcal{M}$  has an algebraic description:

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## Conditions for “ $\mathcal{M} = \mathcal{I} + \mathcal{L}$ ”

- ▶ Require linearity plus closure under powers.
- ▶ Jordan algebra  $\mathcal{J}$ : **linearity** and  $\{A, B\} = AB + BA \in \mathcal{J}$ .  
Equivalent to closure under powers:  $A^2 = \frac{1}{2}(AA + AA)$  and  $(A + B)^2 = A^2 + (AB + BA) + B^2$

- ▶ Symmetric case:

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- ▶ If we demand **both** the Lie and Jordan conditions, we obtain precisely a the matrix algebra case:

$$AB = \frac{1}{2}[A, B] + \frac{1}{2}\{A, B\}$$

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## The end

- ▶ Efficient computations of matrix exponentials?  
e.g. decompose relevant algebra into irreducible components
- ▶ Direct parametrisation of transition matrices?  
i.e. bypass matrix exponentials altogether
- ▶ Insights into why certain results are provable for some models but not others? e.g. the equal-input model

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- ▶ Thanks to the ARC for funding along the way.