On Fisher Information of Some Functions of Phase Type Variates

Pavithra Celeste R and T.G.Deepak

Dept. of Mathematics

Indian Institute of Space Science and Technology

Thiruvananthapuram, Kerala, India

deepak@iist.ac.in

February 13-15, 2019



Distributions of absorption times in a Markov Process with $p<\infty$ transient states (the phases) and one absorbing state.



February 13-15, 2019

Distributions of absorption times in a Markov Process with $p<\infty$ transient states (the phases) and one absorbing state.

Phase type distributions were first considered by Neuts.



Distributions of absorption times in a Markov Process with $p < \infty$ transient states (the phases) and one absorbing state.

Phase type distributions were first considered by Neuts.

M.F. Neuts. Probability distributions of Phase type. In Liber Amicorum

Prof. Emeritus H. Florin, Pages 173-206, 1975.



Distributions of absorption times in a Markov Process with $p < \infty$ transient states (the phases) and one absorbing state.

Phase type distributions were first considered by Neuts.

M.F. Neuts. *Probability distributions of Phase type*. In Liber Amicorum Prof. Emeritus H. Florin, Pages 173-206, 1975.

M.F. Neuts. *Matrix Geometric Solutions in Stochastic Models*, John Hopkins University press, 1981.



Motivations

Dense, in the metric of weak convergence of distributions, in all distributions on $[0,\infty)$.



February 13-15, 2019

Motivations

Dense, in the metric of weak convergence of distributions, in all distributions on $[0,\infty)$.

PH distributions act as the computational vehicle for many applied probability models since they constitute a very versatile class of distributions defined on the non negative real line that lead to models which are algorithmically tractable.



Motivations

Dense, in the metric of weak convergence of distributions, in all distributions on $[0, \infty)$.

PH distributions act as the computational vehicle for many applied probability models since they constitute a very versatile class of distributions defined on the non negative real line that lead to models which are algorithmically tractable.

Their formulation allow us to retain the Markov structure of Stochastic Models while being act as a reasonable approximation to a general distribution.

Continuous Phase type distributions

Let $\{X_t : t \ge 0\}$ be a CTMC on the finite state space $E = \{1, 2,, p, p+1\}$, where the states 1,2,....,p are transient (i.e given that we start in any one of these states, there is a non-zero probability that we will never return to it) and the state p+1 is absorbing.



Continuous Phase type distributions

Let $\{X_t: t \geq 0\}$ be a CTMC on the finite state space $E = \{1, 2,, p, p+1\}$, where the states 1,2,....,p are transient (i.e given that we start in any one of these states, there is a non-zero probability that we will never return to it) and the state p+1 is absorbing. Then $\{X_t: t \geq 0\}$ has an intensity matrix of the form

$$\Lambda = \left[\begin{array}{cc} S & S^0 \\ \mathbf{0} & 0 \end{array} \right]$$

where S is a $p \times p$ dimensional matrix (satisfying $S_{ii} < 0$ and $S_{ij} \ge 0$, for $i \ne j$), and t is a p-dimensional column vector satisfying $Se + s^0 = 0$

February 13-15, 2019

Then $(\beta_1, \beta_2,, \beta_p, \beta_{p+1})$ is called the initial probability vector of $\{X_t : t \ge 0\}$.



Then $(\beta_1, \beta_2,, \beta_p, \beta_{p+1})$ is called the initial probability vector of $\{X_t : t \ge 0\}$.

Let $\tau = \inf \{ t : X_t = p + 1 \}.$



Then $(\beta_1, \beta_2,, \beta_p, \beta_{p+1})$ is called the initial probability vector of $\{X_t : t > 0\}$.

Let $\tau = \inf \{ t : X_t = p + 1 \}.$

Then $\tau \sim PH(\beta, S)$ where $\beta = (\beta_1, \beta_2,, \beta_p)$.



Then $(\beta_1, \beta_2,, \beta_p, \beta_{p+1})$ is called the initial probability vector of $\{X_t : t \ge 0\}$.

Let $\tau = \inf \{ t : X_t = p + 1 \}.$

Then $\tau \sim PH(\beta, S)$ where $\beta = (\beta_1, \beta_2,, \beta_p)$.

• $P\{\tau \le x\} = 1 - \beta exp(Sx)e$



Then $(\beta_1, \beta_2,, \beta_p, \beta_{p+1})$ is called the initial probability vector of $\{X_t : t \ge 0\}$.

Let
$$\tau = \inf \{ t : X_t = p + 1 \}.$$

Then $\tau \sim PH(\beta, S)$ where $\beta = (\beta_1, \beta_2,, \beta_p)$.

- $P\{\tau \le x\} = 1 \beta exp(Sx)e$
- ullet pdf of au is

$$f(x) = \beta \exp(Sx)s^0$$



S. Asmussen, O. Nerman and M. Olsson. Fitting phase-type distributions via the EM algorithm. Scand. J. Statist. 1996, 23, 419-441



- S. Asmussen, O. Nerman and M. Olsson. Fitting phase-type distributions via the EM algorithm. Scand. J. Statist. 1996, 23, 419-441
 - Consider y_1, y_2, \dots, y_M be realization of i.i.d random variables from $PH_p(\beta, S)$



S. Asmussen, O. Nerman and M. Olsson. Fitting phase-type distributions via the EM algorithm. Scand. J. Statist. 1996, 23, 419-441

- Consider $y_1, y_2, ..., y_M$ be realization of i.i.d random variables from $PH_p(\beta, S)$
- Let $x = (x_1, x_2, ..., x_M)$ be the complete data, $\theta = (\beta, S, s^0)$, where $s^0 = -S\mathbf{e}$, be the parameter set and f(.), the pdf of the PH variate



S. Asmussen, O. Nerman and M. Olsson. Fitting phase-type distributions via the EM algorithm. Scand. J. Statist. 1996, 23, 419-441

- Consider $y_1, y_2, ..., y_M$ be realization of i.i.d random variables from $PH_p(\beta, S)$
- Let $x = (x_1, x_2, ..., x_M)$ be the complete data, $\theta = (\beta, S, s^0)$, where $s^0 = -Se$, be the parameter set and f(.), the pdf of the PH variate
- Likelihood function is,

$$L_{f}(\theta; x) = \prod_{i=1}^{p} \beta_{i}^{B_{i}} \prod_{\substack{j=1 \ j \neq i}}^{p} \sum_{j=1}^{N_{ij}} e^{-S_{ij}Z_{i}} \prod_{l=1}^{p} S_{l}^{0N_{l}} e^{-S_{l}^{0}Z_{l}}$$

 B_i , N_i , N_{ij} and Z_i are the sufficient statistics.

- B_i , the number of trajectories that start in phase i, $i = 1, 2, \dots, p$.
- N_i, the number of trajectories for which absorption occurs from phase i, i = 1, 2, · · · , p.
- N_{ij} , the number of transitions that occur from phase i to phase j, $1 \le i, j \le p, i \ne j$.
- Z_i , the total sojourn time in phase i for all the M trajectories combined, for $i = 1, 2, \dots, p$.



$$\hat{S}_{ij} = rac{N_{ij}}{Z_i}, \quad \hat{s}_i^0 = rac{N_i}{Z_i} ext{ and } \hat{eta}_i = rac{B_i}{M}$$



February 13-15, 2019

$$\hat{S}_{ij} = rac{N_{ij}}{Z_i}, \quad \hat{\mathbf{s}}_i^0 = rac{N_i}{Z_i} ext{ and } \hat{eta}_i = rac{B_i}{M}$$

Let θ_0 be any initial value of parameters and I_f be the log-likelihood function.



$$\hat{S}_{ij} = rac{N_{ij}}{Z_i}, \quad \hat{\mathbf{s}}_i^0 = rac{N_i}{Z_i} ext{ and } \hat{eta}_i = rac{B_i}{M}$$

Let θ_0 be any initial value of parameters and I_f be the log-likelihood function.

EM Algorithm works as follows

① E-Step: Calculate $h: \theta \to \mathbb{E}_{\theta_0}(I_f(\theta, x)|Y = y)$



$$\hat{S}_{ij} = rac{N_{ij}}{Z_i}, \quad \hat{\mathbf{s}}_i^0 = rac{N_i}{Z_i} ext{ and } \hat{eta}_i = rac{B_i}{M}$$

Let θ_0 be any initial value of parameters and I_f be the log-likelihood function.

EM Algorithm works as follows

① E-Step: Calculate $h: \theta \to \mathbb{E}_{\theta_0}(I_f(\theta, x)|Y = y)$

② M-Step: $\theta_0 = argmax_\theta h(\theta)$



$$\hat{S}_{ij} = rac{N_{ij}}{Z_i}, \quad \hat{\mathbf{s}}_i^0 = rac{N_i}{Z_i} ext{ and } \hat{eta}_i = rac{B_i}{M}$$

Let θ_0 be any initial value of parameters and I_f be the log-likelihood function.

EM Algorithm works as follows

- **①** E-Step: Calculate $h: \theta \to \mathbb{E}_{\theta_0}(I_f(\theta, x)|Y = y)$
- 2 M-Step: $\theta_0 = argmax_\theta h(\theta)$
- Go to E-Step





Estimates of Sufficient Statistics

Let $M(y, \beta, S) = \int\limits_{0}^{y} e^{S(y-u)} s^{0} \beta e^{Su} du$. Given a sample value y from $PH_{p}(\beta, S)$, we have the following estimates (conditional expectations given y) of the sufficient statistics:

$$\hat{B}_{i}(y,\beta,S) = \frac{\beta_{i}\mathbf{e}_{i}^{\mathsf{T}}e^{Sy}s^{0}}{\beta e^{Sy}s^{0}}$$

$$\hat{Z}_{i}(y,\beta,S) = \frac{M_{ii}(y,\beta,S)}{\beta e^{Sy}s^{0}}$$

$$\hat{N}_{i}(y,\beta,S) = \frac{s_{i}^{0}\beta e^{Sy}\mathbf{e}_{i}}{\beta e^{Sy}s^{0}}$$

$$\hat{N}_{ij}(y,\beta,S) = \frac{S_{ij}M_{ji}(y,\beta,S)}{\beta e^{Sy}s^{0}}$$





1. FSPH Class

V. Ramaswamy, and N. C. Viswanath. "Phase Type Distributions with Finite Support". *Stochastic Models*, 30:576-597, 2014.



1. FSPH Class

V. Ramaswamy, and N. C. Viswanath. "Phase Type Distributions with Finite Support". *Stochastic Models*, 30:576-597, 2014.

Definition

A random variable X has distribution $FSPH_1(\beta, S)$ over the interval (a,b), a < b if it has the same distribution as the random variable a + Ymod(b-a), where $Y \sim PH(\beta, S)$.



1. FSPH Class

V. Ramaswamy, and N. C. Viswanath. "Phase Type Distributions with Finite Support". *Stochastic Models*, 30:576-597, 2014.

Definition

A random variable X has distribution $FSPH_1(\beta, S)$ over the interval (a, b), a < b if it has the same distribution as the random variable a + Ymod(b - a), where $Y \sim PH(\beta, S)$.

Let
$$\mathbf{s}^0 = -S\mathbf{e}$$

•
$$f(x) = \beta e^{S(x-a)} \{ (I - e^{S(b-a)})^{-1} \mathbf{s}^0, a < x < b \}$$





1. FSPH Class

V. Ramaswamy, and N. C. Viswanath. "Phase Type Distributions with Finite Support". *Stochastic Models*, 30:576-597, 2014.

Definition

A random variable X has distribution $FSPH_1(\beta, S)$ over the interval (a,b), a < b if it has the same distribution as the random variable a + Ymod(b-a), where $Y \sim PH(\beta, S)$.

Let
$$\mathbf{s}^0 = -S\mathbf{e}$$

•
$$f(x) = \beta e^{S(x-a)} \{ (I - e^{S(b-a)})^{-1} \mathbf{s}^0, a < x < b \}$$

• Dense in the set of all distributions with support (a, b).



A. Ghosh, R Jana, V Ramaswami, J Rowland, N. K. Shankaranarayanan. Modeling and characterization of large-scale Wi-Fi traffic in public hot-spots. *In: Proc. IEEE INFOCOM* 2011, Sharighai, China, 2921-2929

Definition

The LogPH distribution, $LogPH(\beta, S)$, is defined as the distribution of the random variable $Y = e^X$ where X has a PH distribution with parameters (β, S)



A. Ghosh, R Jana, V Ramaswami, J Rowland, N. K. Shankaranarayanan. Modeling and characterization of large-scale Wi-Fi traffic in public hot-spots. *In: Proc. IEEE INFOCOM* 2011, Sharighai, China, 2921-2929

Definition

The LogPH distribution, $LogPH(\beta, S)$, is defined as the distribution of the random variable $Y = e^X$ where X has a PH distribution with parameters (β, S)

Its density function is

$$f_Y(y) = \frac{1}{y} \beta e^{S \log y} s^0, \quad y \ge 1$$



A. Ghosh, R Jana, V Ramaswami, J Rowland, N. K. Shankaranarayanan. Modeling and characterization of large-scale Wi-Fi traffic in public hot-spots. *In: Proc. IEEE INFOCOM* 2011, Sharighai, China, 2921-2929

Definition

The LogPH distribution, $LogPH(\beta, S)$, is defined as the distribution of the random variable $Y = e^X$ where X has a PH distribution with parameters (β, S)

Its density function is

$$f_Y(y) = \frac{1}{y} \beta e^{S \log y} s^0, \quad y \ge 1$$

Dense in the set of all distribution functions defined on $[1, \infty)$.



A. Ghosh, R Jana, V Ramaswami, J Rowland, N. K. Shankaranarayanan. Modeling and characterization of large-scale Wi-Fi traffic in public hot-spots. *In: Proc. IEEE INFOCOM* 2011, Sharighai, China, 2921-2929

Definition

The LogPH distribution, $LogPH(\beta, S)$, is defined as the distribution of the random variable $Y = e^X$ where X has a PH distribution with parameters (β, S)

Its density function is

$$f_Y(y) = \frac{1}{y} \beta e^{S \log y} s^0, \quad y \ge 1$$

Dense in the set of all distribution functions defined on $[1, \infty)$.

Has many successful uses in the context of queuing and reliability and is used to model insurance data.

Motivation

- Both FSPH and logPH random variates are functions of PH variates.
- Both are dense and have many applications
- The analysis and estimation of functions of PH variates are also important.



Cases Considered

We consider three types of functions.

• The function g(X), of the PH variate X, is differentiable for all X = x and either the derivative at x is strictly positive or negative Example: LogPH Variate



Cases Considered

We consider three types of functions.

- The function g(X), of the PH variate X, is differentiable for all X = x and either the derivative at x is strictly positive or negative Example: LogPH Variate
- The derivative of g is continuous and non zero for all but finite number of values of x and hence for every real number y, there exists n = n(y) inverses .

Example: |X - k|, where $k \in \mathbb{R}^+$



Cases Considered

We consider three types of functions.

- The function g(X), of the PH variate X, is differentiable for all
 X = x and either the derivative at x is strictly positive or negative
 Example: LogPH Variate
- The derivative of g is continuous and non zero for all but finite number of values of x and hence for every real number y, there exists n = n(y) inverses.

Example: |X - k|, where $k \in \mathbb{R}^+$

 Y = g(X) and g is invertible only in a finite interval and at each point y the function is having countable number of inverses Example: FSPH variate, sin(X)

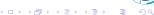
• Let $X \sim PH_p(\beta, S)$



February 13-15, 2019

- Let $X \sim PH_p(\beta, S)$
- Let the function Y = g(X) be differentiable for all X = x and the derivative g' at x is either strictly positive or negative.





- Let $X \sim PH_p(\beta, S)$
- Let the function Y = g(X) be differentiable for all X = x and the derivative g' at x is either strictly positive or negative.
- g will be invertible



- Let $X \sim PH_p(\beta, S)$
- Let the function Y = g(X) be differentiable for all X = x and the derivative g' at x is either strictly positive or negative.
- g will be invertible
- n observations y_1, y_2, \ldots, y_n from $Y \Rightarrow g^{-1}(y_1), g^{-1}(y_2), \ldots, g^{-1}(y_n)$, will be observations from $g^{-1}(Y) = X$, a PH variate





- Let $X \sim PH_p(\beta, S)$
- Let the function Y = g(X) be differentiable for all X = x and the derivative g' at x is either strictly positive or negative.
- g will be invertible
- *n* observations $y_1, y_2, ..., y_n$ from $Y \Rightarrow g^{-1}(y_1), g^{-1}(y_2), ..., g^{-1}(y_n)$, will be observations from $g^{-1}(Y) = X$, a PH variate
- Estimate the parameters of Y using that of X



Let $Y = g(X), X \sim PH_p(\beta, S)$ where, the derivative of g is continuous and non zero for all but finite number of values of x. Then for every y

• there exist a positive integer n = n(y) and real numbers x_1, x_2, \dots, x_n such that, $g[x_k] = y$, $g'[x_k] \neq 0$, $k = 1, 2, \dots, n(y)$.



Let $Y = g(X), X \sim PH_p(\beta, S)$ where, the derivative of g is continuous and non zero for all but finite number of values of x. Then for every y

- there exist a positive integer n = n(y) and real numbers x_1, x_2, \dots, x_n such that, $g[x_k] = y$, $g'[x_k] \neq 0$, $k = 1, 2, \dots, n(y)$.
- 2 there does not exist any x such that g(x) = y or g'(x) = 0 in which case we write n(y) = 0



Let $Y = g(X), X \sim PH_p(\beta, S)$ where, the derivative of g is continuous and non zero for all but finite number of values of x. Then for every y

- 1 there exist a positive integer n = n(y) and real numbers x_1, x_2, \dots, x_n such that, $g[x_k] = y$, $g'[x_k] \neq 0$, $k = 1, 2, \dots, n(y)$.
- ② there does not exist any x such that g(x) = y or g'(x) = 0 in which case we write n(y) = 0

pdf of Y is.

$$h(y) = \begin{cases} \sum_{k=1}^{n} \beta e^{Sx_{k}(y)} s^{0} |g'(x_{k}(y))|^{-1} & n > 0 \\ 0 & n = 0 \end{cases}$$



Given a sample y_1, y_2, \ldots, y_M from Y, we get sample points $x_{11}(y_1), \ldots, x_{1n_1}(y_1), \ldots, x_{M1}(y_M), \ldots, x_{Mn_M}(y_M)$ from X such that $g(x_{il}(y_i)) = y_i, i = 1, 2, \ldots, M$ $l = 1, 2, \ldots, n_i$ where $n_i = n(y_i)$.



February 13-15, 2019

Given a sample y_1, y_2, \dots, y_M from Y, we get sample points

$$x_{11}(y_1), \dots, x_{1n_1}(y_1), \dots, x_{M1}(y_M), \dots, x_{Mn_M}(y_M)$$
 from X such that $g(x_{il}(y_i)) = y_i, i = 1, 2, \dots, M \quad l = 1, 2, \dots, n_i$ where $n_i = n(y_i)$.

$$\hat{B}_{i}(y,\beta,S) = P(X(0) = i|g(X) = y)
= \sum_{k=1}^{n_{y}} |g'(x_{k}(y))|^{-1} \frac{\beta_{i} \mathbf{e}_{i}^{T} \mathbf{e}^{Sx_{k}(y)} s^{0}}{h(y)}
\hat{Z}_{i}(y,\beta,S) = \sum_{k=1}^{n_{y}} |g'(x_{k}(y))|^{-1} \frac{M_{ii}(x_{k}(y),\beta,S)}{h(y)}
\hat{N}_{i}(y,\beta,S) = \sum_{k=1}^{n_{y}} |g'(x_{k}(y))|^{-1} \frac{s_{i}^{0} \beta \mathbf{e}^{Sx_{k}(y)} \mathbf{e}_{i}}{h(y)}
\hat{N}_{ij}(y,\beta,S) = \sum_{k=1}^{n_{y}} |g'(x_{k}(y))|^{-1} \frac{S_{ij} M_{ji}(x_{k}(y),\beta,S)}{h(y)}$$





•
$$Y = g(X), X \sim PH_p(\beta, S)$$



•
$$Y = g(X), X \sim PH_p(\beta, S)$$

ullet g is invertible in an interval of length k



- $Y = g(X), X \sim PH_p(\beta, S)$
- g is invertible in an interval of length k
- at each point y, g has a countable number of inverses, h(y) + l(n) where l(n) = kn m, h(y) is the inverse in the interval of length k





- $Y = g(X), X \sim PH_p(\beta, S)$
- g is invertible in an interval of length k
- at each point y, g has a countable number of inverses, h(y) + I(n) where I(n) = kn m, h(y) is the inverse in the interval of length k
- pdf of Y is

$$f(y) = \sum_{n=0}^{\infty} \beta e^{S(h(y)+kn-m)} s^{0} |h'(y)|$$

= $\beta e^{S(h(y)-m)} (I - e^{Sk})^{-1} s^{0} |h'(y)|$





Define

$$g(n|y) = P(X = h(y) + I(n)|Y = y)$$
$$= \frac{\beta e^{S(h(y) - m)} e^{knS} s^{0}}{f(y)} |h'(y)|$$



Define

$$g(n|y) = P(X = h(y) + I(n)|Y = y)$$

$$= \frac{\beta e^{S(h(y) - m)} e^{knS} s^{0}}{f(y)} |h'(y)|$$
Put $a(y) = e^{S(h(y) - m)} (I - e^{Sk})^{-1} s^{0}$

$$b(y) = \beta e^{S(h(y) - m)} (I - e^{Sk})^{-1}$$
and $c(y) = \frac{|h'(y)|}{\beta a(y)}$



February 13-15, 2019

Define

$$g(n|y) = P(X = h(y) + I(n)|Y = y)$$
$$= \frac{\beta e^{S(h(y) - m)} e^{knS} s^{0}}{f(y)} |h'(y)|$$

Put
$$a(y) = e^{S(h(y)-m)}(I - e^{Sk})^{-1}s^0$$

 $b(y) = \beta e^{S(h(y)-m)}(I - e^{Sk})^{-1}$
and $c(y) = \frac{|h'(y)|}{\beta a(y)}$
then, $\hat{B}_i(y, \beta, S) = c(y)\beta_i a_i(y)$

then,
$$B_i(y,\beta,S)=c(y)eta_ia_i(y)$$

 $\hat{Z}_i(y,\beta,S)=c(y)M_{ii}^*(y,\beta,S)$
 $\hat{N}_i(y,\beta,S)=c(y)s_i^0b_i(y)$
 $\hat{N}_{ij}(y,\beta,S)=c(y)S_{ij}M_{ji}^*(y,\beta,S)$

where $M^*(y, \beta, S) = \sum_{n=0}^{\infty} M(h(y) + kn - m, \beta, S)$



Example

Let $X \sim PH_p(\beta, S)$ and $Y = \sin(X)$.



February 13-15, 2019

Example

Let $X \sim PH_p(\beta, S)$ and $Y = \sin(X)$. Then the pdf of Y is

$$f(y) = \begin{cases} \frac{1}{\sqrt{1 - y^2}} \left[\beta (I - e^{2\pi S})^{-1} \left(e^{\pi S - \sin^{-1}(y)S} + e^{S\sin^{-1}(y)} \right) \right] s^0 & 0 < y < 1 \end{cases}$$

$$\frac{1}{\sqrt{1 - y^2}} \beta \left(I - e^{2\pi S} \right)^{-1} e^{\pi S}$$

$$\left[e^{(\pi + \sin^{-1}(y))S} + e^{-\sin^{-1}(y)S} \right] s^0 & -1 < y < 0$$

$$0 & \text{otherwise}$$

February 13-15, 2019

Define, $E_i = [\mathbf{0} \ \mathbf{0} \ \dots \ \mathbf{0} \ I \ \mathbf{0} \ \dots \ \mathbf{0}]$ and $C = \begin{bmatrix} S & S^0 \beta & \mathbf{0} & \mathbf{0} \\ \mathbf{0} & S & \mathbf{0} & \mathbf{0} \\ \mathbf{0} & \mathbf{0} & S & \mathbf{0} \\ \mathbf{0} & \mathbf{0} & \mathbf{0} & S \end{bmatrix}.$



Estimates of the sufficient statistics are

$$\begin{array}{lcl} \hat{B}_{i}(y,\beta,S) & = & \frac{(1-y^{2})^{-1/2}}{f(y)} \beta_{i} e_{i}^{\mathsf{T}} (I-e^{2\pi S})^{-1} \left[\left(e^{S \sin^{-1}(y)} + \right. \right. \\ & \left. e^{\pi S - S \sin^{-1}(y)} \right) \mathbf{1}_{0 < y < 1} + e^{\pi S} \left(e^{\pi S + \sin^{-1}(y)S} + \right. \\ & \left. e^{-\sin^{-1}(y)S} \right) \mathbf{1}_{-1 < y < 0} \right] s^{0} \\ \hat{N}_{i}(y,\beta,S) & = & \frac{(1-y^{2})^{-1/2}}{f(y)} \beta (I-e^{2\pi S})^{-1} \left[\left(e^{S \sin^{-1}(y)} + \right. \right. \\ & \left. e^{\pi S - S \sin^{-1}(y)} \right) \mathbf{1}_{0 < y < 1} + e^{\pi S} \left(e^{\pi S + \sin^{-1}(y)S} + \right. \\ & \left. e^{-\sin^{-1}(y)S} \right) \mathbf{1}_{-1 < y < 0} \right] e_{i} s_{i}^{0} \end{array}$$



$$\begin{split} \hat{Z}_{i}(y,\beta,S) &= \frac{(1-y^{2})^{-1/2}}{f(y)} \left\{ \left[E_{1}(I-e^{2\pi C})^{-1}e^{\sin^{-1}(y)C}E_{2}^{\mathsf{T}} + \right. \\ &\left. E_{1}(I-e^{2\pi C})^{-1}e^{(\pi-\sin^{-1}(y))C}E_{2}^{\mathsf{T}} \right]_{ji} \mathbf{1}_{0 < y < 1} + \\ &\left[E_{1}(I-e^{2\pi C})^{-1}e^{(\pi-\sin^{-1}(y))C}E_{2}^{\mathsf{T}} + \right. \\ &\left. E_{1}(I-e^{2\pi C})^{-1}e^{(2\pi+\sin^{-1}(y))C}E_{2}^{\mathsf{T}} \right]_{ji} \mathbf{1}_{-1 < y < 0} \right\} \\ \hat{N}_{ij}(y,\beta,S) &= S_{ij} \frac{(1-y^{2})^{-1/2}}{f(y)} \left\{ \left[E_{1}(I-e^{2\pi C})^{-1}e^{\sin^{-1}(y)C}E_{2}^{\mathsf{T}} + \right. \\ &\left. E_{1}(I-e^{2\pi C})^{-1}e^{(\pi-\sin^{-1}(y))C}E_{2}^{\mathsf{T}} \right]_{ji} \mathbf{1}_{0 < y < 1} + \\ &\left. \left[E_{1}(I-e^{2\pi C})^{-1}e^{(\pi-\sin^{-1}(y))C}E_{2}^{\mathsf{T}} \right]_{ji} \mathbf{1}_{-1 < y < 0} \right\} \end{split}$$



 Fisher Information Matrix(FIM) describes the amount of information that the data provide about unknown parameters



- Fisher Information Matrix(FIM) describes the amount of information that the data provide about unknown parameters
- Measures the overall sensitivity of the log-likelihood functions to changes of parameters



- Fisher Information Matrix(FIM) describes the amount of information that the data provide about unknown parameters
- Measures the overall sensitivity of the log-likelihood functions to changes of parameters
- Used for the testing of hypothesis and in the construction of confidence regions for the unknown parameters



• Let *L* be the likelihood function and θ be the parameter vector. The $U = \frac{\partial L}{\partial \theta}$ is called the *score statistic*.



- Let L be the likelihood function and θ be the parameter vector. The $U = \frac{\partial L}{\partial \theta}$ is called the *score statistic*.
- Score statistic is used for inference about parameter values in generalized linear models.



- Let *L* be the likelihood function and θ be the parameter vector. The $U = \frac{\partial L}{\partial \theta}$ is called the *score statistic*.
- Score statistic is used for inference about parameter values in generalized linear models.
- ullet We have, $\mathbb{E}(\mathit{U}) = 0$.



- Let *L* be the likelihood function and θ be the parameter vector. The $U = \frac{\partial L}{\partial \theta}$ is called the *score statistic*.
- Score statistic is used for inference about parameter values in generalized linear models.
- We have, $\mathbb{E}(U) = 0$.
- Variance of U, i.e., $\mathbb{E}(U^2)$ is called the Fisher Information.



- Let *L* be the likelihood function and θ be the parameter vector. The $U = \frac{\partial L}{\partial \theta}$ is called the *score statistic*.
- Score statistic is used for inference about parameter values in generalized linear models.
- We have, $\mathbb{E}(U) = 0$.
- Variance of U, *i.e.*, $\mathbb{E}(U^2)$ is called the Fisher Information.
- The inverse of the Fisher information matrix gives the covariance matrix for the estimates of the parameters.

The expected FIM =
$$E\left[\frac{\partial L(\theta;X)}{\partial \theta} \frac{\partial L(\theta;X)}{\partial \theta^T}\right] = -E\left[\frac{\partial^2 L(\theta;X)}{\partial \theta \ \partial \theta^T}\right]$$



February 13-15, 2019

The expected FIM =
$$E\left[\frac{\partial L(\theta;X)}{\partial \theta} \frac{\partial L(\theta;X)}{\partial \theta^T}\right] = -E\left[\frac{\partial^2 L(\theta;X)}{\partial \theta \ \partial \theta^T}\right]$$

D. Oakes. Direct calculation of the information matrix via the EM. J. R.

Statis. Soc.: Series B (Statistical Methodology). 1999, 61(2), 479-482.

$$\frac{\partial^2 L(\theta; y)}{\partial \theta^2} = \left\{ \frac{\partial^2 Q(\hat{\theta}/\theta)}{\partial \hat{\theta}^2} + \frac{\partial^2 Q(\hat{\theta}/\theta)}{\partial \theta \partial \hat{\theta}} \right\}_{\hat{\theta} = \theta}$$
where $Q(\hat{\theta}/\theta) = E_{\theta} \left(I_{f}(\hat{\theta}; x)/y \right),$



M. Bladt, L. J. Esparza and B. F. Nielsen. Fisher information and statistical inference for phase-type distributions. J. Appl. Prob. Spec. 2011, 48A, 277-293.



M. Bladt, L. J. Esparza and B. F. Nielsen. Fisher information and statistical inference for phase-type distributions. J. Appl. Prob. Spec. 2011, 48A, 277-293.

Let,
$$\theta = (\beta_1, \beta_2, \cdots \beta_{p-1}, s_1^0, S_{12}, \cdots S_{1p}, S_{21}, s_2^0, S_{23} \cdots S_{2p}, \cdots S_{p1}, S_{p2} \cdots S_{p,p-1}, s_p^0)$$

be the parameter vector of order $p - 1 + p^2$.



M. Bladt, L. J. Esparza and B. F. Nielsen. Fisher information and statistical inference for phase-type distributions. J. Appl. Prob. Spec. 2011, 48A, 277-293.

Let,
$$\theta = (\beta_1, \beta_2, \cdots \beta_{p-1}, s_1^0, S_{12}, \cdots S_{1p}, S_{21}, s_2^0, S_{23} \cdots S_{2p}, \cdots S_{p1}, S_{p2} \cdots S_{p,p-1}, s_p^0)$$

be the parameter vector of order $p - 1 + p^2$.

Take
$$\beta_p = 1 - \sum_{j=1}^{p-1} \beta_j$$
 and $S_{ii} = - \sum_{\substack{j=1 \ i \neq i}}^{p} S_{ij} - S_i^0$.



M. Bladt, L. J. Esparza and B. F. Nielsen. Fisher information and statistical inference for phase-type distributions. J. Appl. Prob. Spec. 2011, 48A, 277-293.

Let,
$$\theta = (\beta_1, \beta_2, \cdots \beta_{p-1}, s_1^0, S_{12}, \cdots S_{1p}, S_{21}, s_2^0, S_{23} \cdots S_{2p}, \cdots S_{p1}, S_{p2} \cdots S_{p,p-1}, s_p^0)$$

be the parameter vector of order $p - 1 + p^2$.

Take
$$\beta_p = 1 - \sum_{j=1}^{p-1} \beta_j$$
 and $S_{ii} = -\sum_{\substack{j=1 \ j \neq i}}^p S_{ij} - s_i^0$.

$$Q(\hat{\theta}/\theta) = \sum_{i=1}^{p} \log(\hat{\beta}_{i}) \sum_{k=1}^{n} \hat{B}_{i}^{k} + \sum_{i=1}^{p} \sum_{\substack{j=1\\j\neq i}}^{p} \sum_{k=1}^{n} \log(\hat{S}_{ij}) \hat{N}_{ij}^{k}$$

$$-\sum_{i=1}^{p}\sum_{j=1,j\neq i}^{p}\sum_{k=1}^{n}\hat{S}_{ij}\hat{Z}_{i}^{k}+\sum_{i=1}^{p}\sum_{k=1}^{n}\log(\hat{t}_{i})\hat{N}_{i}^{k}-\sum_{i=1}^{p}\sum_{k=1}^{n}\hat{S}_{i}^{0}$$

$$Q(\hat{\theta}/\theta) = \sum_{i=1}^{p-1} \log(\hat{\beta}_i) U_i \beta_i + \log\left(1 - \sum_{i=1}^{p-1} \hat{\beta}_i\right) U_p (1 - \sum_{i=1}^{p-1} \beta_i) + \sum_{i=1}^{p} \sum_{\substack{j=1 \ i \neq i}}^{p} \log(\hat{S}_{ij}) V_{ij} S_{ij} + \sum_{i=1}^{p} T_i V_{ii} + \sum_{i=1}^{p} \log(\hat{S}_{i}^{0}) W_i S_i^{0}$$

$$U_{i} = \sum_{k=1}^{M} \frac{e_{i}^{\mathsf{T}} e^{Sy_{k}} s^{0}}{f(y_{k})}$$

$$W_{i} = \sum_{k=1}^{M} \frac{\beta e^{Sy_{k}} e_{i}}{f(y_{k})}$$

$$T_i = -\sum_{j=1}^{p} \hat{S}_{ij} - \hat{s_i^0}$$
 $V_{ij} = \sum_{k=1}^{M} (1/f(y_k))(e_j^T M(y_k, \beta, S)e_i).$



For $i, j = 1, 2, \dots, p-1$, the $(i, j)^{th}$ element is

$$\frac{\partial U_i}{\partial \beta_j} - \frac{\partial U_p}{\partial \beta_j}$$



For $i, j = 1, 2, \dots, p-1$, the $(i, j)^{th}$ element is

$$\frac{\partial U_i}{\partial \beta_j} - \frac{\partial U_p}{\partial \beta_j};$$

for $m = 1, 2, \dots, p-1$ and $i, j = 1, 2 \dots p$, the $(ip-1+j, m)^{th}$ element is

$$\frac{\partial U_m}{\partial S_{ij}} - \frac{\partial U_p}{\partial S_{ij}} \text{ if } i \neq j, \ \frac{\partial U_m}{\partial s_i^0} - \frac{\partial U_p}{\partial s_i^0} \text{ if } i = j;$$



For $i, j = 1, 2, \dots, p-1$, the $(i, j)^{th}$ element is

$$\frac{\partial U_i}{\partial \beta_j} - \frac{\partial U_p}{\partial \beta_j};$$

for $m = 1, 2, \dots, p-1$ and $i, j = 1, 2 \dots p$, the $(ip-1+j, m)^{th}$ element is

$$\frac{\partial U_m}{\partial S_{ij}} - \frac{\partial U_p}{\partial S_{ij}} \text{ if } i \neq j, \ \frac{\partial U_m}{\partial s_i^0} - \frac{\partial U_p}{\partial s_i^0} \text{ if } i = j;$$

the $(m, ip - 1 + j)^{th}$ element is given by

$$\frac{\partial V_{ij}}{\partial \beta_m} - \frac{\partial V_{ii}}{\partial \beta_m} \text{ if } i \neq j, \ \frac{\partial W_i}{\partial \beta_m} - \frac{\partial V_{ii}}{\partial \beta_m} \text{ if } i = j;$$



for $i, j, m, n = 1, 2 \cdots p$, the $(ip - 1 + j, mp - 1 + n)^{th}$ element is

$$\frac{\partial V_{ij}}{\partial S_{mn}} - \frac{\partial V_{ii}}{\partial S_{mn}} \text{ if } i \neq j, m \neq n, \qquad \frac{\partial V_{ij}}{\partial S_{m}^{0}} - \frac{\partial V_{ii}}{\partial S_{m}^{0}} \text{ if } i \neq j, m = n, \\ \frac{\partial W_{i}}{\partial S_{mn}} - \frac{\partial V_{ii}}{\partial S_{mn}^{0}} \text{ if } i = j, m \neq n, \qquad \frac{\partial W_{i}}{\partial S_{m}^{0}} - \frac{\partial V_{ii}}{\partial S_{m}^{0}} \text{ if } i = j, m = n.$$



February 13-15, 2019

Computation

For the computation of the above derivatives, put,

$$R_i(u) = \beta e^{Su} e_i$$

and

$$Q_i(u) = e_i^{\mathsf{T}} e^{Su} s^0.$$



Computation

For the computation of the above derivatives, put,

$$R_i(u) = \beta e^{Su} e_i$$

and

$$Q_i(u) = e_i^{\mathsf{T}} e^{Su} s^0.$$

Then we have

$$U_i = \sum_{k=1}^{M} \frac{Q_i(y_k)}{f(y_k)}, \qquad W_i = \sum_{k=1}^{M} \frac{R_i(y_k)}{f(y_k)}, \text{ and}$$





Computation

For the computation of the above derivatives, put,

$$R_i(u) = \beta e^{Su} e_i$$

and

$$Q_i(u) = e_i^{\mathsf{T}} e^{Su} s^0.$$

Then we have

$$U_i = \sum_{k=1}^{M} \frac{Q_i(y_k)}{f(y_k)}, \qquad W_i = \sum_{k=1}^{M} \frac{R_i(y_k)}{f(y_k)}, \text{ and }$$

We need to compute $\frac{\partial Q_i}{\partial \theta_m}, \frac{\partial R_i}{\partial \theta_m}, \frac{\partial f}{\partial \theta_m}, \frac{\partial e^{Su}}{\partial \theta_m}$



Computation of M

We have,

$$M(y,\beta,S) = \int_{0}^{y} e^{S(y-u)} s^{0} \beta e^{Su} du.$$



Computation of M

We have,

$$M(y, \beta, S) = \int\limits_{0}^{y} e^{S(y-u)} s^{0} \beta e^{Su} du.$$

Now using the properties of integration of matrices,

$$M(y, \beta, S) = E_1 e^{Cy} E_2^T$$
, where $E_i = [0 \ 0 \ \dots \ 0 \ / \ 0 \ \dots \ 0]$ and

$$C = egin{bmatrix} S & s^0eta & \mathbf{0} & \mathbf{0} \ \mathbf{0} & S & \mathbf{0} & \mathbf{0} \ \mathbf{0} & \mathbf{0} & S & \mathbf{0} \ \mathbf{0} & \mathbf{0} & \mathbf{0} & S \end{bmatrix}.$$





Computation of M

We have,

$$M(y,\beta,S)=\int\limits_{o}^{y}e^{S(y-u)}s^{0}\beta e^{Su}du.$$
 Now using the properties of integration of matrices,

$$M(y, \beta, S) = E_1 e^{Cy} E_2^T$$
, where $E_i = [\mathbf{0} \ \mathbf{0} \ \dots \ \mathbf{0} \ I \ \mathbf{0} \ \dots \ \mathbf{0}]$ and

$$C = egin{bmatrix} S & s^0eta & \mathbf{0} & \mathbf{0} \ \mathbf{0} & S & \mathbf{0} & \mathbf{0} \ \mathbf{0} & \mathbf{0} & S & \mathbf{0} \ \mathbf{0} & \mathbf{0} & S & \mathbf{0} \ \mathbf{0} & \mathbf{0} & \mathbf{0} & S \end{bmatrix}.$$

For the computation of $\frac{\partial V_{ij}}{\partial \theta_m}$, we need $\frac{\partial e^{Cy}}{\partial \theta_m}$





By uniformization,

$$\frac{\partial e^{Su}}{\partial \theta_m} = \sum_{r=1}^{\infty} b_r \frac{\partial K^r}{\partial \theta_m} + \frac{\partial c}{\partial \theta_m} u e^{Su} (K - I)$$

where, $c = Max\{-S_{ii} : 1 \le i \le p\}$ and $K = \frac{1}{c}S + I$. For $r \ge 1$,

$$\frac{\partial K^r}{\partial \theta_m} = \sum_{l=0}^{r-1} \left[K^l \frac{\partial K}{\partial \theta_m} K^{r-1-l} \right]$$

and

$$\frac{\partial K}{\partial \theta_m} = \frac{1}{c} \frac{\partial S}{\partial \theta_m} - \frac{1}{c^2} \frac{\partial c}{\partial \theta_m} S$$



By uniformization,

$$\frac{\partial e^{Su}}{\partial \theta_m} = \sum_{r=1}^{\infty} b_r \frac{\partial K^r}{\partial \theta_m} + \frac{\partial c}{\partial \theta_m} u e^{Su} (K - I)$$

where, $c = Max\{-S_{ii} : 1 \le i \le p\}$ and $K = \frac{1}{c}S + I$. For $r \ge 1$,

$$\frac{\partial K^r}{\partial \theta_m} = \sum_{l=0}^{r-1} \left[K^l \frac{\partial K}{\partial \theta_m} K^{r-1-l} \right]$$

and

$$\frac{\partial K}{\partial \theta_m} = \frac{1}{c} \frac{\partial S}{\partial \theta_m} - \frac{1}{c^2} \frac{\partial c}{\partial \theta_m} S$$

Assume that the maximum of the diagonal of -S is appeared in row J

$$\frac{\partial \mathbf{c}}{\partial S_{ij}} = \begin{cases} 0 & \text{if} \quad i \neq I, \ j \neq i \\ 1 & \text{if} \quad i = I, \ j \neq i \end{cases}$$

and

$$\frac{\partial c}{\partial s_i^0} = \begin{cases} 0 & \text{if} \quad i \neq I \\ 1 & \text{if} \quad i = I \end{cases}$$



$$\frac{\partial c}{\partial S_{ij}} = \begin{cases} 0 & \text{if} \quad i \neq I, \ j \neq i \\ 1 & \text{if} \quad i = I, \ j \neq i \end{cases}$$

and

$$\frac{\partial \mathbf{c}}{\partial \mathbf{s}_{i}^{0}} = \begin{cases} 0 & \text{if} \quad i \neq I \\ 1 & \text{if} \quad i = I \end{cases}$$

For $i \neq j$

$$\left(\frac{\partial S}{\partial S_{ij}}\right)_{(r,s)} = \begin{cases} 0 & \text{if} \quad i \neq r \\ -1 & \text{if} \quad i = r, j \neq s \\ 1 & \text{if} \quad i = r, j = s \end{cases}$$

and
$$\left(\frac{\partial S}{\partial s_i^0}\right)_{(i,j)} = \begin{cases} -1 & \text{if } i = j \\ 0 & \text{otherwise.} \end{cases}$$





$$\frac{\partial f(y)}{\partial \beta_{m}} = (e_{m}^{\mathsf{T}} - e_{p}^{\mathsf{T}})e^{\mathsf{S}y}s^{0}
\frac{\partial f(y)}{\partial S_{ij}} = \beta \left(\frac{\partial e^{\mathsf{S}y}}{\partial S_{ij}}s^{0} + e^{\mathsf{S}y}\frac{\partial s^{0}}{\partial S_{ij}}\right)
\frac{\partial f(y)}{\partial s_{m}^{0}} = \beta e^{\mathsf{S}y}e_{m} + \beta \frac{\partial e^{\mathsf{S}y}}{\partial s_{m}^{0}}s^{0}$$



February 13-15, 2019

In this case, the FIM of Y = g(X) will be same as the FIM of $g^{-1}(Y)$, which is a PH variate.



In this case, the FIM of Y = g(X) will be same as the FIM of $g^{-1}(Y)$, which is a PH variate.

If $y_1, y_2, ..., y_M$ be a sample from Y, then take the inverse of each observation and compute the *FIM* of the PH variate using the sample $g^{-1}(y_1), g^{-1}(y_2), ..., g^{-1}(y_M)$.



Let y_1, y_2, \ldots, y_M be a sample from Y. Then,

$$\begin{array}{rcl} U_i & = & \displaystyle \sum_{l=1}^{M} \sum_{k=1}^{n_{y_l}} |g'(x_k(y_l))|^{-1} \frac{e_l^{\mathsf{T}} e^{Sx_k(y_l)} s^0}{h(y_l)} \\ W_i & = & \displaystyle \sum_{l=1}^{M} \sum_{k=1}^{n_{y_l}} |g'(x_k(y_l))|^{-1} \frac{\beta e^{Sx_k(y_l)} e_i}{h(y_l)} \\ T_i & = & \displaystyle - \sum_{\substack{j=1 \\ j \neq i}}^{p} \hat{S}_{ij} - \hat{s}_i^0 \\ \\ \text{and } V_{ij} & = & \displaystyle \sum_{k=1}^{M} \sum_{j=1}^{n_{y_l}} \frac{|g'(x_k(y_l))|^{-1}}{h(y_l)} e_j^{\mathsf{T}} M(x_k(y_l), \beta, S) e_i. \end{array}$$





We have,
$$M^*(y, \beta, S) = \sum_{n=0}^{\infty} M(h(y) + kn - m, \beta, S)$$



We have,
$$M^*(y, \beta, S) = \sum_{n=0}^{\infty} M(h(y) + kn - m, \beta, S)$$

Which can be computed as
$$M^*(y, \beta, S) = E_1 e^{C(h(y) - m)} (I - e^{Ck})^{-1} E_2^{\mathsf{T}}.$$





We have,
$$M^*(y, \beta, S) = \sum_{n=0}^{\infty} M(h(y) + kn - m, \beta, S)$$

Which can be computed as $M^*(y, \beta, S) = E_1 e^{C(h(y) - m)} (I - e^{Ck})^{-1} E_2^{\mathsf{T}}$.
Also, $M^*(y, \beta, S) = (I - e^{Sk})^{-1} M(h(y) - m, \beta, S) + (I - e^{Sk})^{-1} M(k, \beta, S) (I - e^{Sk})^{-1} e^{S(h(y) - m)}$



$$\begin{array}{lcl} U_{i} & = & \displaystyle \sum_{l=1}^{n} \frac{|h'(y)|e_{i}^{\mathsf{T}}e^{S(h(y_{l})-m)}(I-e^{Sk})^{-1}s^{0}}{f(y_{l})} \\ W_{i} & = & \displaystyle \sum_{l=1}^{n} \frac{|h'(y)|\beta e^{S(h(y)-m)}(I-e^{Sk})^{-1}e_{i}}{f(y_{l})} \\ T_{i} & = & \displaystyle -\sum_{j=1,\,j\neq i}^{p} \hat{S}_{ij} - \hat{s}_{i}^{0} \\ V_{ij} & = & \displaystyle \sum_{l=1}^{n} \frac{|h'(y)|e_{j}^{\mathsf{T}}M^{*}(y_{l},\beta,S)e_{i}}{f(y_{l})} \end{array}$$





$$R_i(u) = \beta e^{Su} (I - e^{Sk})^{-1} e_i$$



$$R_i(u) = \beta e^{Su} (I - e^{Sk})^{-1} e_i$$

and

$$Q_i(u) = e_i^{\mathsf{T}} e^{Su} (I - e^{Sk})^{-1} s^0$$



$$R_i(u) = \beta e^{Su} (I - e^{Sk})^{-1} e_i$$

and

$$Q_i(u) = e_i^{\mathsf{T}} e^{Su} (I - e^{Sk})^{-1} s^0$$

Hence we get,

$$U_i = \sum_{l=1}^n \frac{|h'(y)|}{f(y_l)} Q_i(h(y_l) - m)$$

$$W_i = \sum_{l=1}^n \frac{|h'(y)|}{f(y_l)} R_i(h(y_l) - m)$$





$$R_i(u) = \beta e^{Su} (I - e^{Sk})^{-1} e_i$$

and

$$Q_i(u) = e_i^{\mathsf{T}} e^{Su} (I - e^{Sk})^{-1} s^0$$

Hence we get,

$$U_{i} = \sum_{l=1}^{n} \frac{|h'(y)|}{f(y_{l})} Q_{i}(h(y_{l}) - m)$$

$$W_{i} = \sum_{l=1}^{n} \frac{|h'(y)|}{f(y_{l})} R_{i}(h(y_{l}) - m)$$

and

$$V_{ij} = \sum_{l=1}^{n} \frac{|h'(y)|}{f(y_l)} E_1 e^{C(h(y)-m)} (I - e^{kC})^{-1} E_2^{\mathsf{T}} e_i$$



For $q \in \{1, 2, \dots, p-1+p^2\}$,

$$\frac{\partial U_{i}}{\partial \theta_{q}} = \sum_{l=1}^{n} \frac{|h'(y)|}{(f(y_{l}))^{2}} \left[f(y_{l}) \frac{\partial Q_{i}(h(y_{l}) - m)}{\partial \theta_{q}} - (Q_{i}h(y_{l}) - m) \frac{\partial f(y_{l})}{\partial \theta_{q}} \right]
\frac{\partial W_{i}}{\partial \theta_{q}} = \sum_{l=1}^{n} \frac{|h'(y)|}{(f(y_{l}))^{2}} \left[f(y_{l}) \frac{\partial R_{i}(h(y_{l}) - m)}{\partial \theta_{q}} - (R_{i}h(y_{l}) - m) \frac{\partial f(y_{l})}{\partial \theta_{q}} \right]
\frac{\partial V_{ij}}{\partial \theta_{q}} = \sum_{l=1}^{n} \frac{|h'(y)|}{(f(y_{l}))^{2}} \left\{ f(y_{l}) E_{1} \left[\frac{\partial}{\partial \theta_{q}} (e^{C(h(y) - m)}) (I - e^{kC})^{-1} + H^{-1} \right] \right\}$$

$$\frac{1}{I-1} (I(y_I))^{L} \left(\frac{\partial \theta_q}{\partial \theta_q} e^{C(h(y)-m)} \frac{\partial}{\partial \theta_q} (I - e^{kC})^{-1} \right] E_2^{\mathsf{T}} e_i + \frac{\partial f(y_I)}{\partial \theta_q} E_1 e^{C(h(y)-m)} \left((I - e^{kC})^{-1} E_2^{\mathsf{T}} e_i \right)$$



Differentiating the pdf, we get,

$$\begin{split} \frac{\partial f}{\partial \beta_q} &= |h'(y)| \left[e_q^\intercal e^{S(h(y)-m)} (I-e^{Sk})^{-1} s^0 - \right. \\ & \left. e_p^\intercal e^{S(h(y)-m)} (I-e^{Sk})^{-1} s^0 \right] \\ \frac{\partial f}{\partial S_{ij}} &= |h'(y)| \left[\beta \frac{\partial}{\partial S_{ij}} (e^{S(h(y)-m)}) (I-e^{Sk})^{-1} s^0 + \right. \\ & \left. \beta e^{S(h(y)-m)} \frac{\partial}{\partial S_{ij}} (I-e^{Sk})^{-1} s^0 \right] \\ \text{and} & \frac{\partial f}{\partial s_q^0} &= |h'(y)| \left[\beta e^{S(h(y)-m)} (I-e^{Sk})^{-1} e_q + \beta \frac{\partial}{\partial s_q^0} (e^{S(h(y)-m)}) (I-e^{Sk})^{-1} s^0 + \beta e^{S(h(y)-m)} \frac{\partial}{\partial s_q^0} (I-e^{Sk})^{-1} s^0 \right]. \end{split}$$

February 13-15, 2019

Thus for evaluating the above derivatives we need the terms

$$rac{\partial}{\partial S_{ij}}(I-e^{Sk})^{-1} \text{ and } rac{\partial}{\partial s_q^0}(I-e^{Sk})^{-1}.$$



Thus for evaluating the above derivatives we need the terms

$$rac{\partial}{\partial S_{ij}}(I-e^{Sk})^{-1}$$
 and $rac{\partial}{\partial s_q^0}(I-e^{Sk})^{-1}.$ By uniformization,

$$\frac{\partial}{\partial \theta_{q}} (I - e^{Sk})^{-1} = \sum_{n=1}^{\infty} \frac{\partial e^{nkS}}{\partial \theta_{q}}$$

$$= \sum_{n=1}^{\infty} \sum_{r=1}^{\infty} b_{r,nk} \frac{\partial K^{r}}{\partial \theta_{q}} + \sum_{n=1}^{\infty} \frac{\partial c}{\partial \theta_{q}} nke^{nkS} (K - I).$$





Thus for evaluating the above derivatives we need the terms

$$\frac{\partial}{\partial S_{ij}}(I-e^{Sk})^{-1}$$
 and $\frac{\partial}{\partial s_{o}^{0}}(I-e^{Sk})^{-1}.$ By uniformization,

$$\frac{\partial}{\partial \theta_{q}} (I - e^{Sk})^{-1} = \sum_{n=1}^{\infty} \frac{\partial e^{nkS}}{\partial \theta_{q}}$$

$$= \sum_{n=1}^{\infty} \sum_{r=1}^{\infty} b_{r,nk} \frac{\partial K^{r}}{\partial \theta_{q}} + \sum_{n=1}^{\infty} \frac{\partial c}{\partial \theta_{q}} nke^{nkS} (K - I).$$

Hence,

$$\frac{\partial}{\partial \theta_q} (I - e^{Sk})^{-1} = \sum_{r=1}^{\infty} \sum_{r=1}^{\infty} b_{r,kn} \frac{\partial K^r}{\partial \theta_q} + \frac{\partial c}{\partial \theta_q} e^{Sk} (I - e^{Sk})^{-2} (K - I).$$





FSPH

10000 observations are taken from the beta B(0.5, 5) distribution.



FSPH

10000 observations are taken from the beta B(0.5,5) distribution. Fit this data with a $FSPH_1(\alpha, T)$ variate of order 2 and the approximate ML estimates are

$$\alpha = [0.5531 \ 0.4469]$$



FSPH

10000 observations are taken from the beta B(0.5,5) distribution. Fit this data with a $FSPH_1(\alpha,T)$ variate of order 2 and the approximate ML estimates are

$$\alpha = [0.5531 \ 0.4469]$$

and

$$T = \begin{bmatrix} -9.6181 & 1.0762 \\ 12.6514 & -66.7070 \end{bmatrix}.$$



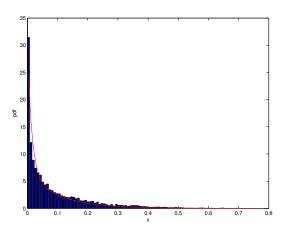


Figure : B(0.5,5) fitted with $FSPH_1(\alpha, T)$ of order 2.



Table : Correlations for B(0.5, 5) fitted with $FSPH_1$.

Parameter	$\hat{lpha_1}$	$\hat{t_1}$	<i>T</i> ₁₂	$\hat{\mathcal{T}_{21}}$	$\hat{t_2}$
$\hat{lpha_1}$	1.0000	-0.1879	0.3353	0.5468	-0.1594
$\hat{t_1}$	-0.1879	1.0000	0.9344	-0.9101	-0.5402
$\hat{T_{12}}$	0.3353	0.9344	1.0000	0.3193	0.1711
$\hat{T_{21}}$	0.5468	-0.9101	0.3193	1.0000	0.9228
$\hat{t_2}$	-0.1594	-0.5402	0.1711	0.9228	1.0000



